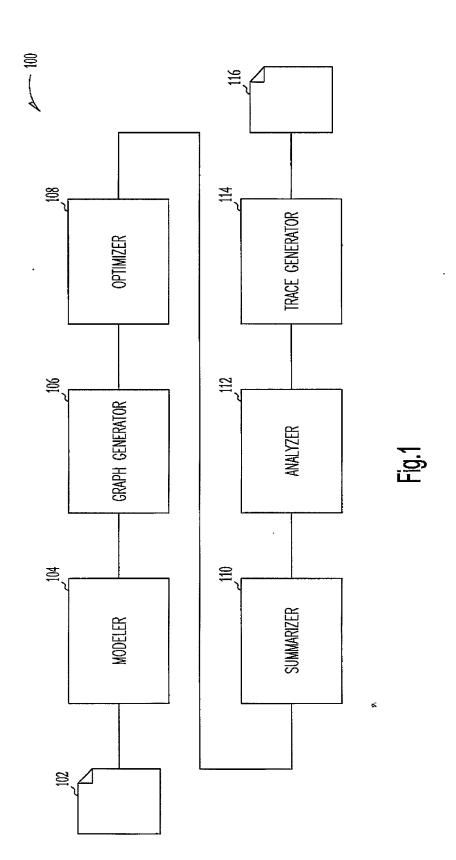
1/13



	•	2/13
bool nUO;	<pre>void getUnit() bool cE:=F; if (nU0) {    if (?) {      ;       nU0:=F;       cE:=T; }</pre>	} else cE:=T; if (cE) if (nU0) ]; else ]
	[65] [61]	[7] [8] [9] [10] [11]
	<b>~</b>	,
bool nu0;	<pre>void getUnit() if (nU0) { if (?) {    ;     nU0:=F;    ; }</pre>	} else ; if (?) { if (nU0) ]; else .];
н	[1] [5] [6]	[7] [8] [9] [10] [11]
	<b>~</b>	,
	<pre>void getUnit() [1] [2] if (?) { [3] if (?) { [4]; [5]; [6] }</pre>	} else [7]; [8] if (?) [10] if (?) [11];  B <sub>1</sub>
int numUnits; int level:	<pre>void getUnit() {   bool canEnter := F;   if (numUnits = 0) {     if (level &gt; 10) {       NewUnit();       numUnits := 1;       canEnter := T; }</pre>	<pre>} else canEnter := T; if (canEnter) if (numUnits = 0) assert(F); else gotUnit(); }</pre>
⁴न ∗न	[1] [2] [4] [6]	[7] [8] [9] [10] [11]

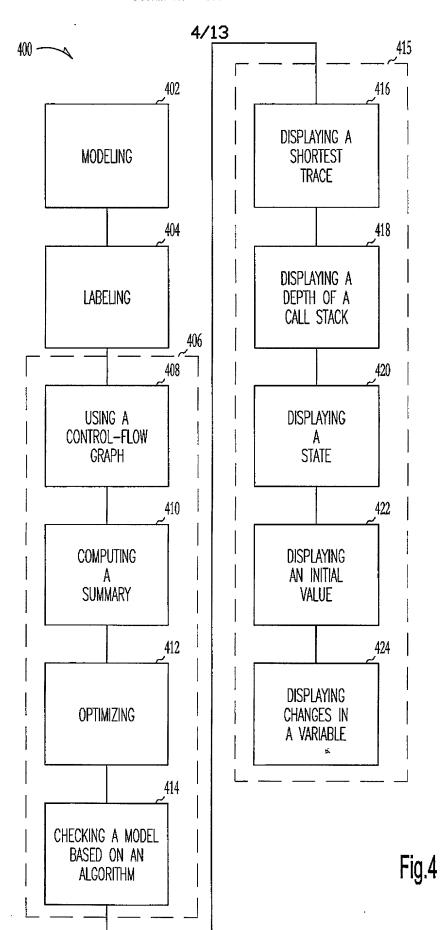
**Fig.**2

3/13

300

```
302 -
                                                                 -304
      decl g;
                         bebop v1.0: (c) Microsoft Corporation.
                         Done creating bdd variables
                         Done building transition relations
      main()
      begin
        decl h;
                         Label R reachable by following path:
[6]
        h := !g;
[7]
        \lambda(g,h);
                         Line 12
                                             State g=1 h=0
[8]
                         Line 11
        skip;
                                             State g=1 h=0
                         Line 10
[9]
        \lambda(g,h);
                                             State g=1 h=0
                              Line 22
[10]
        skip;
                                             State g=1 a1=1 a2=0
        if (g) then
[11]
                                   Line 24
                                             State g=1 a1=0 a2=1
[12]
      R: skip;
                                   Line 20
                                             State g=1 a1=0 a2=1
        else
                              Line 21
                                             State g=1 a1=1 a2=0
[14]
         skip;
                              Line 20
                                             State g=1 a1=1 a2=0
        fi
                         Line 9
                                             State g=1 h=0
      end
                         Line 8
                                             State g=1 h=0
                              Line 22
                                             State g=1 a1=1 a2=0
      A(a1,a2)
                                   Line 24
                                             State g=1 a1=0 a2=1
      begin
                                   Line 20
                                             State g=1 a1=0 a2=1
[20]
                                             State g=1 a1=1 a2=0
        if (a1) then
                              Line 21
[21]
         A(a2,a1);
                              Line 20
                                             State g=1 a1=1 a2=0
[22]
         skip;
                         Line 7
                                             State g=1 h=0
        else
                         Line 6
                                             State g=1
[24]
         g := a2;
        fi
      end
```

Fig.3



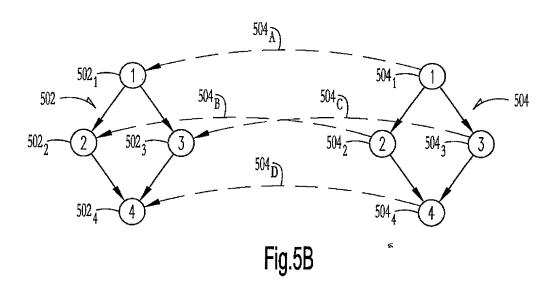
5/13

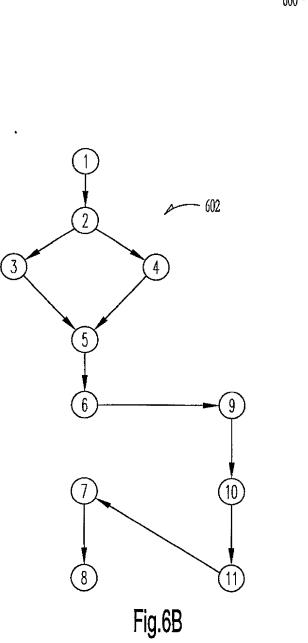
500

He had the been seen that the seen the

[1] if (z) {
[2] x:=1;
else
[3] x:=z;
[4] z:=y|x;

Fig.5A





```
Boolean g;
main() {
  if (z) {
600 -
                  [1]
[2]
[3]
                                   x:=1;
                                else
                  [4]
                                   x:=0;
                  [5]
                                z:=y+x;
                                foo (z);
skip;
                  [6]
                  [7]
                  [8]
                  [9]
[10]
[11]
                              foo (z) {
                                g:=1;
```

Fig.6A

7/13

700

702	ν	Transfer,
	skip print goto return	$\lambda(\Omega_1,\Omega_2).(\Omega_2=\Omega_1)$
704	$x_1, \dots, x_k := e_1, \dots, e_k$	$\lambda \langle \Omega_1, \Omega_2 \rangle . (\Omega_2 = \Omega_1 [x_1 / \Omega_1(e_1)] [x_k / \Omega_1(e_k)])$
706—	if(d) while(d) assert(d)	Transfer <sub>v,true</sub> = $\lambda(\Omega_1, \Omega_2)$ , $((\Omega_1(d) = 1) \land (\Omega_2 = \Omega_1))$ Transfer <sub>v,true</sub> = $\lambda(\Omega_1, \Omega_2)$ , $((\Omega_1(d) = 0) \land (\Omega_2 = \Omega_1))$
708	pr(e1,, e4)	$\lambda_1^{\Omega_1,\Omega_2}.(\Omega_2=\Omega_1 [x_1/\Omega_1(e_1)][x_t/\Omega_1(e_k)]),$ where $x_1,,x_t$ are the formal parameters of pr

Fig.7

800



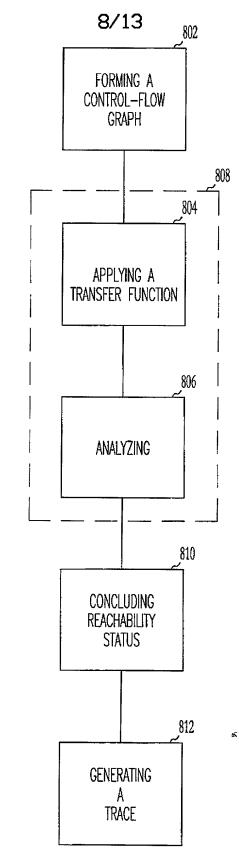
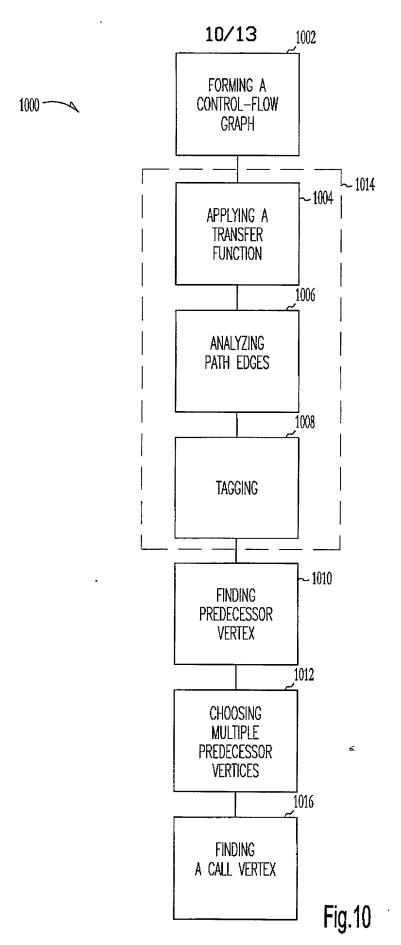


Fig.8

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```
global
      PathEdges,SummaryEdges,WorkList
                                                                                    <del>--</del> 900
904 procedure Propagate(v,p)
       begin
  9% — if p ⊄ PathEdges(v) then
     908 \neg PathEdges(v) := PathEdges(v) \cup p
     910 Insert v into WorkList fi
912-
      end
914 procedure Reachable(GB)
      begin
  916 for all v \in V_B do PathEdges(v) := {}
  917 for all v \in Call_B do SummaryEdges(v) := {}
  918 PathEdges(First#(main)) :=
            \{\langle \Omega, \Omega \rangle \mid \Omega \text{ is any valuation to globals and local variables of main}\}
         WorkList := \{First_B(main)\}
         while WorkList \neq 0 do
    924 remove vertex v from WorkList
           switch (v)
       928 case v \in Call_B
                Propagate(sSucce(v), SelfLoop(Join(PathEdges(v), Transfer,)))
                Propagate(ReturnPt_B(v), Join(PathEdges(v), SummaryEdges(v)))
              case v \in Exit_B:
                for each w \in Succ_B(v) do
                   let
                     c \in Call_B such that w = ReturnPt_B(c) and
                     s = Lift_c(PathEdges(v), ProcOf_B(v)) \longrightarrow 940
                     if s & SummaryEdges(c) then 944
                       SummaryEdges(c) := SummaryEdges(c) \cup s
                       Propagate(w.Join(PathEdges(c),SummaryEdges(c)));
                  ni
       950 -
              case v \in Cond_B:
                Propagate(Tsucc<sub>B</sub>(v), Join(PathEdges(v), Transfer<sub>v,true</sub>))
                Propagate(Fsucc<sub>B</sub>(v), Join(PathEdges(v), Transfer<sub>v, false</sub>))
              case v \in V_B - Call<sub>B</sub> - Exit<sub>B</sub> - Cond<sub>B</sub>:
                let p = Join(PathEdges(v), Transfer_v) in 958
                  for each w \in Succ_B(v) do 960
                     Propagate(w,p) \( \text{90} \)
                ni
                                                                     Fig.9
      end
```



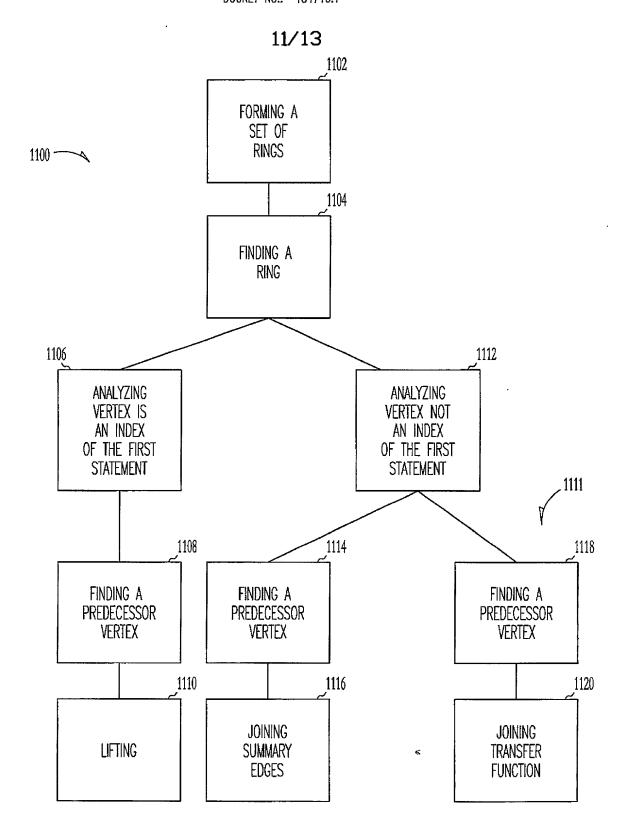


Fig.11

#### 12/13

```
global
PE': V_G \rightarrow \text{set-of } (D \times D)
 Worklist V_G \rightarrow \text{set-of}(D \times D)
procedure Propagate(v : V_{G,p} : (D \times D))
begin
   if p \notin PE'(v) then
       \overrightarrow{PE'}(v) := PE'(v) \cup \{p\}
       Worklist(v) := Worklist(v) \cup \{p\}
   fi
end
procedure CMOP_{SP_{rhs}}(S : set-of D)
begin
   \overrightarrow{PE}' (entry) := {\langle d, d \rangle \mid d \in S}
   Worklist (entry) := PE' (entry)
   while \exists v_2 \text{ s.t. } Worklist(v_2) \neq 0 \text{ do}
      select and remove \langle d_1, d_2 \rangle from Worklist(v_2)
      for each v_2 \rightarrow v_3 \in E_G do
         for each d_3 \in M(v_2 \rightarrow v_3)(\{d_2\}) do
            Propagate(v_3 \langle d_1, d_3 \rangle)
         od
      od
   od
end
```

### 13/13

```
global
PE': V \rightarrow \text{set-of D x set-of D}
Worklist: V_G \rightarrow \text{set-of D} \times \text{set-of D}
procedure Propagate(V:V_{G,p}: (set-of D x set-of D))
begin
  if p \notin PE'(v) then
     PE'(v) := PE'(v) \cup \{\rho\}
      Worklist(v) := Worklist(v) \cup \{\rho\}
  fi
end
procedure CSMOP SP<sub>ths</sub> (S': set-of (set-of D))
begin
  PE' (entry := \{\langle S, S \rangle \mid S \in S'\}
     Worklist (entry) := PE' (entry)
     while \exists v_2 \text{ s.t. } Worklist(v_2) \neq 0 do
        select and remove \langle S_1, S_2 \rangle from Worklist(v_2)
        for each V_2 \rightarrow V_3 \in E_G do
          let S_3 = M(v_2 \to v_3)(S_2) in
             Propagate(v_3, \langle S_1, S_3 \rangle)
          ni
        od
     od
  end
```